# **Correlation-based imaging in random media**

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with George Papanicolaou (Stanford University), Knut Sølna (UC Irvine).

- Principle of sensor array imaging:
- probe an unknown medium with waves,
- record the waves transmitted through or reflected by the medium,

- process the recorded data to extract relevant information about some features of the medium.

# Reflector imaging through a homogeneous medium



• Sensor array imaging of a reflector located at  $\vec{y}$ .  $\vec{x}_s$  is a source,  $\vec{x}_r$  is a receiver. Measured data:  $\{u(t, \vec{x}_r; \vec{x}_s), r = 1, \dots, N_r, s = 1, \dots, N_s\}$ .

• Mathematical model:

$$\left(\frac{1}{c_0^2} + \frac{1}{c_{\rm ref}^2} \mathbf{1}_{B_{\rm ref}}(\vec{\boldsymbol{x}} - \vec{\boldsymbol{y}})\right) \frac{\partial^2 u}{\partial t^2}(t, \vec{\boldsymbol{x}}; \vec{\boldsymbol{x}}_{\rm s}) - \Delta_{\vec{\boldsymbol{x}}} u(t, \vec{\boldsymbol{x}}; \vec{\boldsymbol{x}}_{\rm s}) = f(t)\delta(\vec{\boldsymbol{x}} - \vec{\boldsymbol{x}}_{\rm s})$$

• Purpose of imaging: using the measured data, build an imaging function  $\mathcal{I}(\vec{y}^S)$  that would ideally look like  $\frac{1}{c_{\text{ref}}^2} \mathbf{1}_{B_{\text{ref}}}(\vec{y}^S - \vec{y})$ , in order to extract the relevant information  $(\vec{y}, B_{\text{ref}}, c_{\text{ref}})$  about the reflector.

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# • Classical imaging functions:

1) Least-Squares imaging: minimize the quadratic misfit between measured data and synthetic data obtained by solving the wave equation with a candidate  $(\vec{y}_{\text{test}}, B_{\text{test}}, c_{\text{test}}).$ 

2) Reverse Time imaging: simplify Least-Squares imaging by "linearization" of the forward problem.

3) Kirchhoff Migration: simplify Reverse Time imaging by substituting travel time migration for full wave equation.

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2) Reverse Time imaging: simplify Least-Squares imaging by "linearization" of the forward problem.

3) Kirchhoff Migration: simplify Reverse Time imaging by substituting travel time migration for full wave equation.

• Kirchhoff Migration function:

$$\mathcal{I}_{\mathrm{KM}}(\vec{\boldsymbol{y}}^{S}) = \sum_{r=1}^{N_{\mathrm{r}}} \sum_{s=1}^{N_{\mathrm{s}}} u \big( \mathcal{T}(\vec{\boldsymbol{x}}_{s}, \vec{\boldsymbol{y}}^{S}) + \mathcal{T}(\vec{\boldsymbol{y}}^{S}, \vec{\boldsymbol{x}}_{r}), \vec{\boldsymbol{x}}_{r}; \vec{\boldsymbol{x}}_{s} \big)$$

It forms the image with the superposition of the backpropagated traces.  $\mathcal{T}(\vec{y}^S, \vec{x})$  is the travel time from  $\vec{x}$  to  $\vec{y}^S$ , i.e.  $\mathcal{T}(\vec{y}^S, \vec{x}) = |\vec{y}^S - \vec{x}|/c_0$ .

- Very robust with respect to measurement noise [1].

- Sensitive to clutter noise (due to scattering medium): If the medium is scattering, then Kirchhoff Migration (usually) does not work.

[1] H. Ammari, J. Garnier, and K. Sølna, Waves in Random and Complex Media 22, 40 (2012).

## **Reflector imaging through a scattering medium**



• Sensor array imaging of a reflector located at  $\vec{y}$ .  $\vec{x}_s$  is a source,  $\vec{x}_r$  is a receiver. Data:  $\{u(t, \vec{x}_r; \vec{x}_s), r = 1, \dots, N_r, s = 1, \dots, N_s\}.$ 

$$\left(\frac{1}{c^2(\vec{\boldsymbol{x}})} + \frac{1}{c_{\rm ref}^2} \mathbf{1}_{B_{\rm ref}}(\vec{\boldsymbol{x}} - \vec{\boldsymbol{y}})\right) \frac{\partial^2 u}{\partial t^2}(t, \vec{\boldsymbol{x}}; \vec{\boldsymbol{x}}_{\rm s}) - \Delta_{\vec{\boldsymbol{x}}} u(t, \vec{\boldsymbol{x}}; \vec{\boldsymbol{x}}_{\rm s}) = f(t)\delta(\vec{\boldsymbol{x}} - \vec{\boldsymbol{x}}_{\rm s})$$

• Random medium model:

 $\frac{1}{c^2(\vec{x})} = \frac{1}{c_0^2} (1 + \mu(\vec{x}))$ 

 $c_0$  is a reference speed,

 $\mu(\vec{x})$  is a zero-mean random process.



#### Edinburgh

# Imaging through a randomly scattering medium: strategy

• A multiscale analysis is possible in different asymptotic regimes (small wavelength, large propagation distance, small correlation length, ...).

• In the limit the wave equation with random coefficients is replaced by a stochastic partial differential equation driven by Brownian fields; for instance, an Itô-Schrödinger equation in the paraxial regime.

• Stochastic calculus can then be used.

• Compute the mean and variance of an imaging function  $\mathcal{I}(\vec{y}^S)$ .  $\hookrightarrow$  resolution and stability analysis.

• The mean imaging function  $\vec{y}^S \to \mathbb{E}[\mathcal{I}(\vec{y}^S)]$  characterizes the precision in the localization and characterization of the reflector (resolution).

• Criterium for statistical stability:

$$\mathrm{SNR} := \frac{\mathbb{E} \left[ \mathcal{I}(\vec{\boldsymbol{y}}^S) \right]}{\mathrm{Var} \left( \mathcal{I}(\vec{\boldsymbol{y}}^S) \right)^{1/2}} > 1$$

 $\hookrightarrow$  design the imaging function to get good trade-off between stability and resolution.

- General results obtained by a multiscale analysis.
- The mean wave is small while the wave fluctuations are large.

 $\implies$  The Kirchhoff Migration function (or Reverse Time imaging function) is unstable in randomly scattering media.

• The wave fluctuations at nearby points and nearby frequencies are correlated. The wave correlations carry information about the medium.

 $\implies$  One can use local cross correlations for imaging.

• More detailed results depend on the scattering regime.

• Consider the time-harmonic form of the scalar wave equation  $(\vec{x} = (x, z))$ 

$$(\partial_z^2 + \Delta_\perp)\hat{u} + \frac{\omega^2}{c_0^2} (1 + \mu(\boldsymbol{x}, z))\hat{u} = 0.$$

Consider the paraxial regime " $\lambda \ll l_c \ll L$ ":

$$\omega \to \frac{\omega}{\varepsilon^4}, \qquad \mu(\boldsymbol{x}, z) \to \varepsilon^3 \mu(\frac{\boldsymbol{x}}{\varepsilon^2}, \frac{z}{\varepsilon^2}).$$

The function  $\hat{\phi}^{\varepsilon}$  (slowly-varying envelope of a plane wave) defined by

$$\hat{u}^{\varepsilon}(\omega, \boldsymbol{x}, z) = e^{i\frac{\omega z}{\varepsilon^4 c_0}} \hat{\phi}^{\varepsilon}\left(\omega, \frac{\boldsymbol{x}}{\varepsilon^2}, z\right)$$

satisfies

$$\boldsymbol{\varepsilon}^{4}\partial_{z}^{2}\hat{\phi}^{\varepsilon} + \left(2i\frac{\omega}{c_{0}}\partial_{z}\hat{\phi}^{\varepsilon} + \Delta_{\perp}\hat{\phi}^{\varepsilon} + \frac{\omega^{2}}{c_{0}^{2}}\frac{1}{\varepsilon}\mu(\boldsymbol{x},\frac{z}{\varepsilon^{2}})\hat{\phi}^{\varepsilon}\right) = 0.$$

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• In the regime  $\varepsilon \ll 1$ , the forward-scattering approximation in direction z is valid and  $\hat{\phi} = \lim_{\varepsilon \to 0} \hat{\phi}^{\varepsilon}$  satisfies the Itô-Schrödinger equation [1]

$$2i\frac{\omega}{c_0}\partial_z\hat{\phi} + \Delta_{\perp}\hat{\phi} + \frac{\omega^2}{c_0^2}\dot{B}(\boldsymbol{x},z)\hat{\phi} = 0$$

with  $B(\boldsymbol{x}, z)$  Brownian field  $\mathbb{E}[B(\boldsymbol{x}, z)B(\boldsymbol{x}', z')] = \gamma(\boldsymbol{x} - \boldsymbol{x}') \min(z, z'),$  $\gamma(\boldsymbol{x}) = \int_{-\infty}^{\infty} \mathbb{E}[\mu(\boldsymbol{0}, 0)\mu(\boldsymbol{x}, z)]dz.$ 

[1] J. Garnier and K. Sølna, Ann. Appl. Probab. 19, 318 (2009).

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$$d\hat{\phi} = \frac{ic_0}{2\omega} \Delta_{\perp} \hat{\phi} dz + \frac{i\omega}{2c_0} \hat{\phi} \circ dB(\boldsymbol{x}, z)$$

with  $B(\boldsymbol{x}, z)$  Brownian field  $\mathbb{E}[B(\boldsymbol{x}, z)B(\boldsymbol{x}', z')] = \gamma(\boldsymbol{x} - \boldsymbol{x}') \min(z, z'),$  $\gamma(\boldsymbol{x}) = \int_{-\infty}^{\infty} \mathbb{E}[\mu(\boldsymbol{0}, 0)\mu(\boldsymbol{x}, z)]dz.$ 

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$$d\hat{\phi} = \frac{ic_0}{2\omega} \Delta_{\perp} \hat{\phi} dz + \frac{i\omega}{2c_0} \hat{\phi} dB(\boldsymbol{x}, z) - \frac{\omega^2 \gamma(\mathbf{0})}{8c_0^2} \hat{\phi} dz$$

with  $B(\boldsymbol{x}, z)$  Brownian field  $\mathbb{E}[B(\boldsymbol{x}, z)B(\boldsymbol{x}', z')] = \gamma(\boldsymbol{x} - \boldsymbol{x}') \min(z, z'),$  $\gamma(\boldsymbol{x}) = \int_{-\infty}^{\infty} \mathbb{E}[\mu(\boldsymbol{0}, 0)\mu(\boldsymbol{x}, z)]dz.$ 

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• We introduce the fundamental solution  $\hat{G}(\omega, (\boldsymbol{x}, z), (\boldsymbol{x}_0, z_0))$ :

$$d\hat{G} = \frac{ic_0}{2\omega} \Delta_{\perp} \hat{G} dz + \frac{i\omega}{2c_0} \hat{G} \circ dB(\boldsymbol{x}, z)$$

starting from  $\hat{G}(\omega, (\boldsymbol{x}, z = z_0), (\boldsymbol{x}_0, z_0)) = \delta(\boldsymbol{x} - \boldsymbol{x}_0).$ 

• In a homogeneous medium  $(B \equiv 0)$  the fundamental solution is

$$\hat{G}_0(\omega,(\boldsymbol{x},z),(\boldsymbol{x}_0,z_0)) = \frac{\exp\left(\frac{i\omega|\boldsymbol{x}-\boldsymbol{x}_0|^2}{2c_0|z-z_0|}\right)}{2i\pi c_0\frac{|z-z_0|}{\omega}}$$

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• In a random medium, by Itô's formula

$$\mathbb{E}\big[\hat{G}\big(\omega,(\boldsymbol{x},z),(\boldsymbol{x}_0,z_0)\big)\big] = \hat{G}_0\big(\omega,(\boldsymbol{x},z),(\boldsymbol{x}_0,z_0)\big)\exp\Big(-\frac{\gamma(\boldsymbol{0})\omega^2|z-z_0|}{8c_0^2}\Big),$$

where  $\gamma(\boldsymbol{x}) = \int_{-\infty}^{\infty} \mathbb{E}[\mu(\boldsymbol{0}, 0)\mu(\boldsymbol{x}, z)]dz.$ 

• Strong damping of the mean wave.

 $\implies$  Reverse Time imaging and Kirchhoff migration fail.

• In a random medium, by Itô's formula

$$egin{aligned} &\mathbb{E}ig[\hat{G}ig(\omega,(oldsymbol{x},z),(oldsymbol{x}_0,z_0)ig)\overline{\hat{G}ig(\omega,(oldsymbol{x}',z),(oldsymbol{x}_0,z_0)ig)}ig] \ &=\hat{G}_0ig(\omega,(oldsymbol{x},z),(oldsymbol{x}_0,z_0)ig)\overline{\hat{G}_0ig(\omega,(oldsymbol{x}',z),(oldsymbol{x}_0,z_0)ig)}\expig(-rac{\gamma_2(oldsymbol{x}-oldsymbol{x}')\omega^2|z-z_0|}{4c_0^2}ig), \end{aligned}$$

where  $\gamma_2(\boldsymbol{x}) = \int_0^1 \gamma(\boldsymbol{0}) - \gamma(\boldsymbol{x}s) ds$  (note  $\gamma_2(\boldsymbol{0}) = 0$ ).

- The fields at nearby points are correlated.
- Same results in frequency: The fields at nearby frequencies are correlated.
- $\implies$  One should migrate local cross correlations for imaging.

• In a random medium, by Itô's formula

$$egin{aligned} &\mathbb{E}ig[\hat{G}ig(\omega,(oldsymbol{x},z),(oldsymbol{x}_0,z_0)ig)\overline{\hat{G}ig(\omega,(oldsymbol{x}',z),(oldsymbol{x}_0,z_0)ig)}ig] \ &=\hat{G}_0ig(\omega,(oldsymbol{x},z),(oldsymbol{x}_0,z_0)ig)\overline{\hat{G}_0ig(\omega,(oldsymbol{x}',z),(oldsymbol{x}_0,z_0)ig)}\expig(-rac{\gamma_2(oldsymbol{x}-oldsymbol{x}')\omega^2|z-z_0|}{4c_0^2}ig), \end{aligned}$$

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• The fields at nearby points are correlated.

- Same results in frequency: The fields at nearby frequencies are correlated.
- $\implies$  One should migrate local cross correlations for imaging.

• In a random medium, by Itô's formula, one can write a closed-form equation for the *n*-th order moment.

Depending on the statistics of the random medium, the wave fluctuations may have Gaussian statistics or not [1].

[1] J. Garnier and K. Sølna, to appear in Comm. Part. Differ. Equat.

# Application: Imaging below an "overburden"



Imaging below an "overburden" From van der Neut and Bakulin (2009)

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## Imaging below an overburden



 $\vec{y}$ 

Array imaging of a reflector at  $\vec{y}$ .  $\vec{x}_s$  is a source,  $\vec{x}_r$  is a receiver. Data:  $\{u(t, \vec{x}_r; \vec{x}_s), r = 1, \dots, N_r, s = 1, \dots, N_s\}.$ 

If the "overburden" is scattering, then Kirchhoff Migration does not work:

$$\mathcal{I}_{\mathrm{KM}}(\vec{\boldsymbol{y}}^{S}) = \sum_{r=1}^{N_{\mathrm{r}}} \sum_{s=1}^{N_{\mathrm{s}}} u \big( \mathcal{T}(\vec{\boldsymbol{x}}_{s}, \vec{\boldsymbol{y}}^{S}) + \mathcal{T}(\vec{\boldsymbol{y}}^{S}, \vec{\boldsymbol{x}}_{r}), \vec{\boldsymbol{x}}_{r}; \vec{\boldsymbol{x}}_{s} \big)$$

# Numerical simulations



Computational setup

-1500 -1600 -1700 -1800 -1800 -1900 -2000 -2000 -2000 -2000 -2000 -2000 -2000 -100 0 100 200300

### Image obtained with Kirchhoff Migration

(simulations carried out by Chrysoula Tsogka)

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Imaging below an overburden



 $\vec{y}$  .

 $\vec{x}_s$  is a source,  $\vec{x}_r$  is a receiver. Data:  $\{u(t, \vec{x}_r; \vec{x}_s), r = 1, \dots, N_r, s = 1, \dots, N_s\}$ .

Image with Kirchhoff Migration of the cross correlation matrix:

$$\mathcal{I}(ec{oldsymbol{y}}^S) = \sum_{r,r'=1}^{N_{\mathrm{r}}} \mathcal{C}ig(\mathcal{T}(ec{oldsymbol{x}}_r, ec{oldsymbol{y}}^S) + \mathcal{T}(ec{oldsymbol{y}}^S, ec{oldsymbol{x}}_{r'}), ec{oldsymbol{x}}_r, ec{oldsymbol{x}}_{r'}ig),$$

with

$$C(\tau, \vec{x}_r, \vec{x}_{r'}) = \sum_{s=1}^{N_s} \int u(t, \vec{x}_r; \vec{x}_s) u(t + \tau, \vec{x}_{r'}; \vec{x}_s) dt , \qquad r, r' = 1, \dots, N_r$$

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# Numerical simulations







Kirchhoff Migration

## Cross Correlation Migration

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# Analysis in randomly scattering media

Does the cross correlation imaging function give good images in scattering media ?
→ It is possible to analyze the resolution and stability of the imaging function in randomly scattering media:

- analysis in the random paraxial regime,
- analysis in the randomly layered regime,
- analysis in the radiative transfer regime.
- General results:

Imaging function is stable provided the bandwidth is large enough and/or the source array is large enough.

Resolution is essentially independent of the size of the source array.

• Detailed results: Clarify the role of scattering.

- in the random paraxial regime, scattering helps (it enhances the angular diversity of the illumination).

- in the randomly layered regime, scattering does not help (it reduces the angular diversity of the illumination).

[1] J. Garnier and G. Papanicolaou, Inverse Problems 28 075002 (2012).



- Assume that:
- the source aperture is b and the receiver aperture is a.
- there is a point reflector at  $\vec{y} = (y, -L_y)$ .
- the covariance function  $\gamma(\boldsymbol{x}) = \int \mathbb{E}[\mu(\boldsymbol{0}, 0)\mu(\boldsymbol{x}, z)]dz$  can be expanded as  $\gamma(\boldsymbol{x}) = \gamma(\boldsymbol{0}) - \bar{\gamma}_2 |\boldsymbol{x}|^2 + o(|\boldsymbol{x}|^2)$  for small  $|\boldsymbol{x}|$ .
- scattering is strong:  $\frac{\gamma(\mathbf{0})\omega_0^2 L}{c_0^2} > 1$  ( $\rightarrow$  mean wave is damped).



Homogeneous medium

Random medium

Effective source aperture:

$$b_{\text{eff}} = b$$
  $b_{\text{eff}} = \left(b^2 + \frac{\bar{\gamma}_2 L^3}{3}\right)^{1/2}$ 



Homogeneous medium

Random medium

Effective source aperture:

$$b_{\rm eff} = b$$
  $b_{\rm eff} = \left(b^2 + \frac{\bar{\gamma}_2 L^3}{3}\right)^{1/2}$ 

Effective receiver aperture:

$$a_{\text{eff}} = b \frac{L_y - L}{L_y} \qquad \qquad a_{\text{eff}} = b_{\text{eff}} \frac{L_y - L}{L_y}$$

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• The imaging function for the search point  $\vec{y}^S$  is

$$\mathcal{I}(\vec{\boldsymbol{y}}^S) = \frac{1}{N_r^2} \sum_{r,r'=1}^{N_r} \mathcal{C}\big(\mathcal{T}(\vec{\boldsymbol{x}}_r, \vec{\boldsymbol{y}}^S) + \mathcal{T}(\vec{\boldsymbol{y}}^S, \vec{\boldsymbol{x}}_{r'}), \vec{\boldsymbol{x}}_r, \vec{\boldsymbol{x}}_{r'}\big)$$

• The imaging function is statistically stable  $(\lambda_0 \ll b \ll L)$ .

• The lateral resolution is  $\frac{\lambda_0(L_y - L)}{a_{\text{eff}}}$ . The range resolution is  $\frac{c_0}{B}$ . Here:  $\lambda_0$  is the carrier wavelength, B is the bandwidth.

- Since  $a_{\text{eff}} \mid_{\text{rand}} > a_{\text{eff}} \mid_{\text{homo}}$ , this shows that scattering helps.
- physical reason: scattering enhances the angular diversity of the illumination.
- effect already noticed for time-reversal experiments, in which the recorded waves are time-reversed and sent back in the real medium.

# Randomly layered medium

• Random medium model  $(\vec{x} = (x, z))$ :

$$\frac{1}{c^2(\vec{x})} = \frac{1}{c_0^2} (1 + \mu(z))$$

 $c_0$  is a reference speed,

 $\mu(z)$  is a zero-mean random process.



• Consider the time-harmonic form of the scalar wave equation  $(\vec{x} = (x, z))$ 

$$(\partial_z^2 + \Delta_\perp)\hat{u} + \frac{\omega^2}{c_0^2} (1 + \mu(z))\hat{u} = 0$$

Consider the scaled regime " $l_c \ll \lambda \ll L$ ":

$$\omega o rac{\omega}{arepsilon}, \qquad \mu(z) o \muigl(rac{z}{arepsilon^2}igr)$$

The moments of the random Green's function are known in the limit  $\varepsilon \to 0$  [1].

[1] J.-P. Fouque, J. Garnier, G. Papanicolaou, and K. Sølna, Wave propagation ..., Springer, 2007.



- Assume that:
- the source aperture is b and the receiver aperture is a.
- there is a point reflector at  $\vec{y} = (y, -L_y)$ .

- the localization length  $L_{loc}$  is smaller than L (strong scattering, mean wave is damped):

$$L_{\text{loc}} = \frac{4c_0^2}{\gamma\omega_0^2}, \qquad \gamma = \int_{-\infty}^{\infty} \mathbb{E}[\mu(0)\mu(z)]dz$$



Homogeneous medium

Randomly layered medium

Effective source aperture:

$$b_{\rm eff} = b \qquad \qquad b_{\rm eff}^2 = 4L_{\rm loc}L \ (\ll b^2)$$



Homogeneous medium

Randomly layered medium

Effective source aperture:

$$b_{\rm eff} = b \qquad \qquad b_{\rm eff}^2 = 4L_{\rm loc}L \ (\ll b^2)$$

Effective receiver aperture:

$$a_{\text{eff}} = b \frac{L_y - L}{L_y} \qquad \qquad a_{\text{eff}} = b_{\text{eff}} \frac{L_y - L}{L_y}$$

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• The imaging function for the search point  $\vec{y}^{S}$  is

$$\mathcal{I}(\vec{\boldsymbol{y}}^{S}) = \frac{1}{N_{\mathrm{r}}^{2}} \sum_{r,r'=1}^{N_{\mathrm{r}}} \mathcal{C}\big(\mathcal{T}(\vec{\boldsymbol{x}}_{r},\vec{\boldsymbol{y}}^{S}) + \mathcal{T}(\vec{\boldsymbol{y}}^{S},\vec{\boldsymbol{x}}_{r'}),\vec{\boldsymbol{x}}_{r},\vec{\boldsymbol{x}}_{r'}\big)$$

• The imaging function is statistically stable  $(\lambda_0 \ll b, L)$ .

• The lateral resolution is 
$$\frac{\lambda_0(L_y - L)}{a_{\text{eff}}}$$
. The range resolution is  $\frac{c_0}{B} \left(1 + \frac{B^2 L}{4\omega_0^2 L_{\text{loc}}}\right)^{1/2}$ .

Since a<sub>eff</sub> |<sub>rand</sub> < a<sub>eff</sub> |<sub>homo</sub>, this shows that scattering does not help.
physical reason: scattering reduces the angular and frequency diversity of the illumination.

# **Further results**

• Use of other imaging functions based on cross-correlations (or Wigner distribution functions).

• Use of ambient noise sources.

One can apply correlation-based imaging techniques to signals emitted by ambient noise sources (increasingly popular in geophysics, "seismic interferometry").

 $\hookrightarrow$  Travel time tomography (surface wave tomography since 2005, body waves more recently).

 $\hookrightarrow$  Volcano monitoring (early warning of the eruption of Le Piton de la Fournaise in october 2010).

 $\hookrightarrow$  Passive reflector imaging.

• Use of higher-order correlations.

One can apply imaging techniques based on special fourth-order cross correlations. Useful when the statistics of the wave fluctuations is not Gaussian.

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### Passive sensor imaging of a reflector

- Ambient noise sources ( $\circ$ ) emit stationary random signals.
- The signals  $(u(t, \vec{x}_r))_{r=1,...,N_r}$  are recorded by the receivers  $(\vec{x}_r)_{r=1,...,N_r}$  ( $\blacktriangle$ ).
- The cross correlation matrix is computed and migrated:

$$\mathcal{I}(\vec{\boldsymbol{y}}^{S}) = \sum_{r,r'=1}^{N_{r}} \mathcal{C}_{T} \big( \mathcal{T}(\vec{\boldsymbol{x}}_{r'}, \vec{\boldsymbol{y}}^{S}) + \mathcal{T}(\vec{\boldsymbol{x}}_{r}, \vec{\boldsymbol{y}}^{S}), \vec{\boldsymbol{x}}_{r}, \vec{\boldsymbol{x}}_{r'} \big)$$

with 
$$\mathcal{C}_T(\tau, \vec{\boldsymbol{x}}_r, \vec{\boldsymbol{x}}_{r'}) = \frac{1}{T} \int_0^T u(t + \tau, \vec{\boldsymbol{x}}_{r'}) u(t, \vec{\boldsymbol{x}}_r) dt$$



Provided the ambient noise illumination is long (in time) and diversified (in angle and frequency): good stability [1].

[1] J. Garnier and G. Papanicolaou, SIAM J. Imaging Sciences 2, 396 (2009).

# Conclusions



 $\vec{y}$ 

- In scattering media one should migrate *well chosen* cross correlations of data, not data themselves.
- Method can be applied with ambient noise sources instead of controlled sources.
- Scattering can help ! Already noticed for time-reversal experiments, but far from clear in imaging problems.

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## **Perspectives**

• Space surveillance and imaging with airborne passive synthetic aperture arrays.

